Zachary Yoder

Professional Experience

Research Scientist | Max Planck Institute for Intelligent Systems, Stuttgart, Germany

- Led cross-functional hardware development cycles on emergent, electrostatic soft transducers for high-voltage wearable devices and robotic systems.
- Assembled, tested, and iterated on electromechanical hardware, using collected data and models to inform design.
- Developed MATLAB interfaces for test control and data acquisition, characterizing force-stroke, lifetime, electrical properties, and dynamics of flexible actuators and sensors; adopted by 40+ team members across 10+ projects.
- Strategically positioned research findings to field experts, leading to five publications in top journals.
- Presented to diverse audiences and created visual media expressing research impact, earning seven awards, over 90,000 YouTube views, and invitations for talks and panel moderation.
- Translated user requirements into functional specifications for high-voltage amplifiers, achieving a cost reduction of 65%. **Key Projects**

Designed high-speed modules for reconfigurable robots

- Science Robotics
- Used first-principles modeling to quide design.
- _ Learned Eagle to design untethered high-voltage electronics.

Created soft, electrohydraulic haptic devices with diverse feedback Advanced Science - Designed a robust high-voltage

safety approach with IRB approval. - Developed a full-stack user interface for a psychophysical study.

Graduate Research Assistant | University of Colorado, Boulder, CO

- Designed, fabricated, and evaluated high-speed prosthetic fingers driven by electrostatic artificial muscles, modeling the kinematic linkage system to optimize geometric parameters.

New Product Development Engineering Co-op | MSA Safety, Cranberry, PA

- Designed components and conducted validation testing for highly-regulated supplied air respirators, identifying and escalating persistent hardware failure modes to engineering and design teams.
- Applied finite element analysis to identify stress concentrations in plastic hose clips, informing component and mold design.

Leadership Experience

Advisor for Bachelor's Thesis | University of Esslingen, Esslingen, Germany

Mentored a bachelor's thesis on proprioceptive soft grippers using impedance spectroscopy and machine learning, training the student in scientific writing and presentation; the thesis won an award.

Teaching assistant | University of Colorado, Boulder, CO

- Manufacturing Processes and Systems lab instructor, training students in design for manufacturing, GD&T, engineering drawing, and life cycle analysis; taught labs, held office hours, and graded assignments.
- President, Pitt Club Triathlon | University of Pittsburgh, Pittsburgh, PA
 - Grew membership 140%, increased budget 333% and tripled the number of club races.

Awards

Best demo (EuroEAP 2024) | Best poster (Multi-modal robots workshop, IEEE Robosoft 2024) | Second most 'kudos cards' (Colleague appreciation program, 2023) | Best poster (Soft grippers workshop, IEEE Robosoft 2023) | Best presentation (5th workshop on perception, IROS 2022) | Best presentation (CU graduate research symposium 2020) | Second-best product pitch (Randall Family innovation and product pitching competition 2016, \$15,000 award)

Education

PhD in Engineering Science University of Stuttgart, Stuttgart, Germany	2021 - present
Research carried out at Max Planck Institute for Intelligent Systems under Christoph Keplinger and Katherine Kuchenbecker.	
MS in Mechanical Engineering University of Colorado, Boulder, CO	2019 - 2021
BS in Mechanical Engineering University of Pittsburgh, Pittsburgh, PA Summa cum laude	2015 - 2019
Minor in Computer Science University of Pittsburgh, Pittsburgh, PA	2016 - 2019

Skills

Software: SolidWorks, OnShape, Adobe Premiere Pro, Affinity Designer, National Instruments, Microsoft Office Programming languages: MATLAB, Python, Java

Prototyping: 3D printing, laser-cutting, high-voltage electronics, fixture design, screen and flexography printing, hand tools Test equipment: DAQs, load cells, torque sensors, laser-displacement sensors, tensile testers, muscle levers, multimeters, oscilloscopes, waveform generators, LCR meters, high-voltage amplifiers, high-speed cameras

Actuator characterization: force-stroke behavior, specific energy and power, dynamics, power consumption, capacitive sensing Materials characterization: electrochemical impedance spectroscopy, dielectric breakdown, tensile testing, clean room Communication: presentations, demonstrations, product pitches, visual media

with object size detection Advanced Functional Materials - Utilized impedance spectroscopy for

Developed versatile soft grippers

- high-voltage capacitance sensing. Developed algorithms for pick
 - detection and size estimation.

2019 - 2021

2021 - present

2017 - 2018

2017 - 2018

Fall 2019

Fall 2023